



NEWS RELEASE [Witt-NR-01-2019_SmartRemoval] January 7, 2019

Machine downtimes reduced by 10 % – with no extra costs!

Minimization of unproductive downtimes is a top priority for injection molding machine operators, since this is the only way to have the investment in the machine amortized in the shortest possible time. The WITTMANN **W8** and **WX** robot generations come with the patented **SmartRemoval** function as standard, which automatically shortens the time required for parts removal from the mold area without any operator intervention.



Visualizations of SmartRemoval Move In (left) and SmartRemoval Move Out on the WITTMANN R8 robot control system.

The advantages are obvious: shortening of the unproductive time plus lower total energy consumption for the system through reduction of the heat loss caused by the mold standing open for any length of time, which ultimately also contributes to more consistent process quality. Here, the injection molding process as such is basically left completely untouched, since *SmartRemoval* only influences the time required to remove the part from the machine. All parameters set on the processing machine remain unchanged.

How does the patented WITTMANN SmartRemoval function work?

The **R8** and **R9** robot control systems from WITTMANN automatically calculate from the first cycle how long the mold opening movement will take. Then, in all subsequent parts removal processes, the system no longer waits for the complete opening of the moving mold half, but instead already starts to move the vertical axis of the WITTMANN robot beforehand, just like the "flying start" known from motor sport. At the moment when the mold is fully opened, the axis is already moving at an optimal speed and can be accelerated still further for the actual removal process inside the



open mold area. So, in contrast to the conventional sequential removal process, the gripper of the robot arrives earlier at the position where the transfer of the molded part takes place.

The synchronization with the ejectors functions in a similar way. Based on previous automatic measurements, the WITTMANN robot already issues the ejector signal before it arrives at the parts removal position, so that when it reaches that position it can take over the parts directly without having to wait for the ejectors' response. This process is designated as "Move In". In the subsequent "Move Out" phase, the ideal timing to send the machine the "close mold" signal – before the WITTMANN robot has moved completely out of the mold area – is calculated in a similar way. The aim of these measures is to eliminate from the process the delays caused by electrical signal transmission. The patented **SmartRemoval** function is included in the standard scope of delivery for WITTMANN **R8** and **R9** control systems.

SIMPLE-PICK-AND-PLACE_PRG MANUAL MODE	Operator 07:34 PM	SIMPLE-PICK-AND-PLACE,PRG MANUAL MODE	Operator 07:34 PM
? SmartRemoval		SmartRemoval	
Move-In	Move-Out	Move-In	Move-Out
Axis sequence		Axis sequence	
First move Y-Axis	×	First move X-Axis	T
Second move X-Axis	•	Second move Y-Axis	v
Takeout position	123 👳	Position above mold	123 👳
Y-Axis: 1100.0		X-Axis: 132.0	
X-Axis: 150.0		Y -Axis: 10.0	
Distance	(A) (I)	Distance	123 💿
The distance before the X-Takeout position, where the Y-M to the takeout position with a straight movement.	ovement must be finsihed, in order for X to travel	The distance from the X-Takeout position, where the away from its takeout position using a straight motion	Y movement is started, after the X-Axis moved
۵X: 0.0		ΔΧ: 0.0	
Time	123 💿	Time	923 🕘
This is the time before the takeout position is reached with acknowledges itself, thus starting the teach commands after	Y and X, when the command SmartRemoval r itself, before it is actually finished.	This is the time before the position above mold is real on the permit to close the mold, in order to eliminate Δt 0.0 s	ched, when the command SmartRemoval already turns any switching delays of the machine interface.
0126. SmartRemoval IN: Takeout position: Y: 11 X: 150.0; ΔX: 0.0 R; ΔI: 0.0 s	10.0 Cancel OK	0126. SmartRemoval OUT: Position above Y: 10.0; AX: 0.0 R; At: 0.0 s	mold: X: 132.0 Cancel OK

Input mask for SmartRemoval Move In (left) and SmartRemoval Move Out on the WITTMANN R9 robot control system.

What savings are possible?

In an identical program sequence with, say, 1.0 s parts removal time, 0.2 s can be saved by using a small robot from the **W818*** series, that is, about 20%. With larger models, such as the WITTMANN **WX173**** robot, a shortened parts removal time of 1.2 s instead of 1.7 s is reached in similar test arrangements, that is, a reduction of almost 30%!

Remarks:

- * Mainly for injection molding machines with 80 to 200 t clamping force.
- ** Mainly for injection molding machines with 600 to 2,400 t clamping force.



The WITTMANN Group is a worldwide leader in the manufacturing of injection molding machines, robots and peripheral equipment for the plastics industry. Headquartered in Vienna/Austria, the WITTMANN Group consists of two main divisions, WITTMANN BATTENFELD and WITTMANN, which operate 8 production facilities in 5 countries, including 34 direct subsidiary offices located in all major plastics markets around the world.

WITTMANN BATTENFELD focuses on the independent market growth in the manufacturing of state-of-the-art injection molding machines and process technology, providing a modern and comprehensive range of machinery in a modular design that meets the actual and future requirements of the plastic injection molding market. WITTMANN's product range includes robots and automation systems, material handling systems, dryers, gravimetric and volumetric blenders, granulators, mold temperature controllers and chillers. With this comprehensive range of peripheral equipment, WITTMANN can provide plastics processors with solutions that cover all production requirements, ranging from autonomous work cells to integrated plantwide systems.

The syndication of the WITTMANN Group has led to connectivity between all product lines, providing the advantage plastics processors have been looking for in terms of a seamless integration of injection molding machines, automation and auxiliary equipment – all occurring at a progressive rate.

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